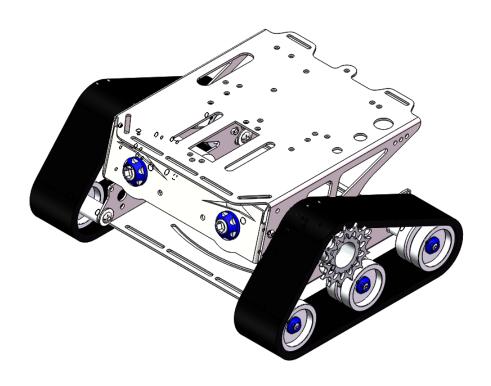
#### **Keenlon Iron Man-4 Thacked Chassis**

## **Mechanical Assembly Guide Revision 1.0**



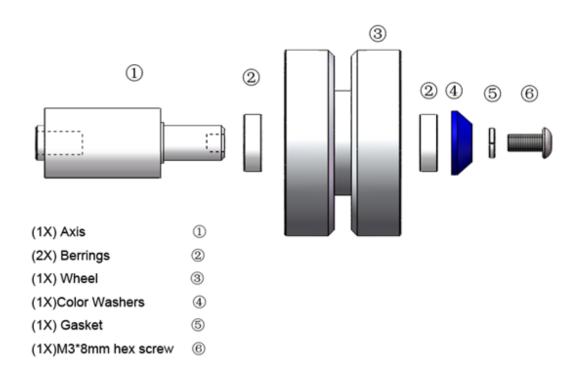
**Safety first!** Wear eye protection and never touch a powered robot! **Warning!** Chassis is made of stainless steel with sharp edges, be careful!

Design & Executive Shanghai Keenlon Hi-Tech Co., Ltd.

Service Techsupport@keenlon.com

Website www.keenlon.com

STEP 1A
Driven wheel Sub-assembly

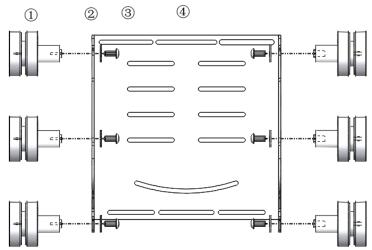


STEP 1B



STEP 2A

Driven wheels Sub-assembly

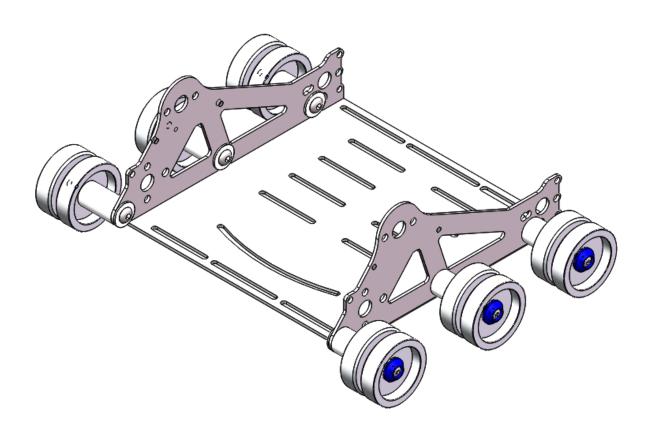


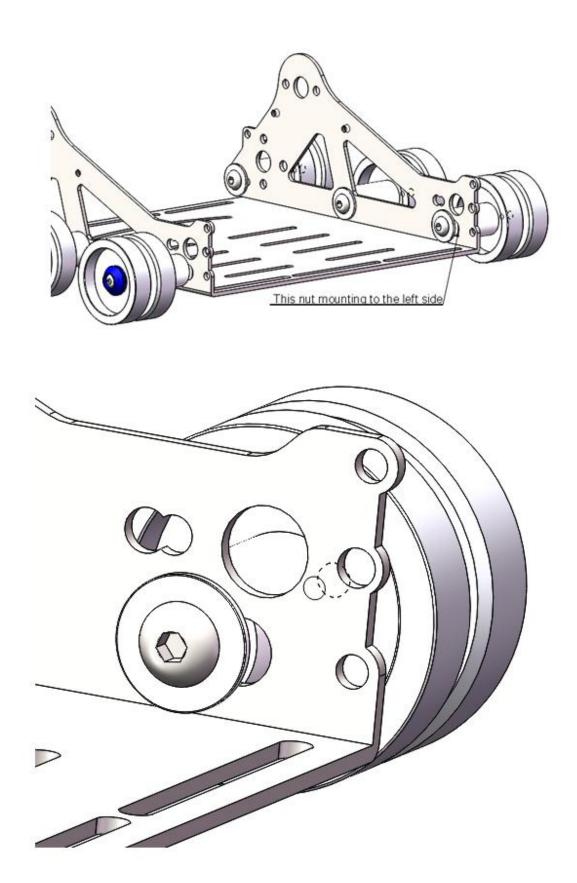
- (6X) Driven wheels
- (6X) M4\*1mm gasket

1

2

- (6X) M4\*8mm hex screws ③
- (1X) Chassis ④





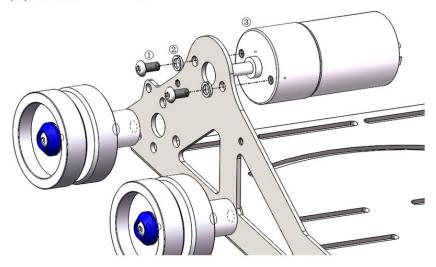
NOTE: This is a "secret screw". Do not tighten the screw too much now!

STEP 3A(2X)

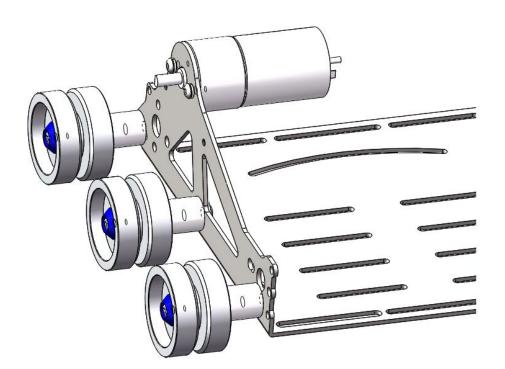
Gear Motor

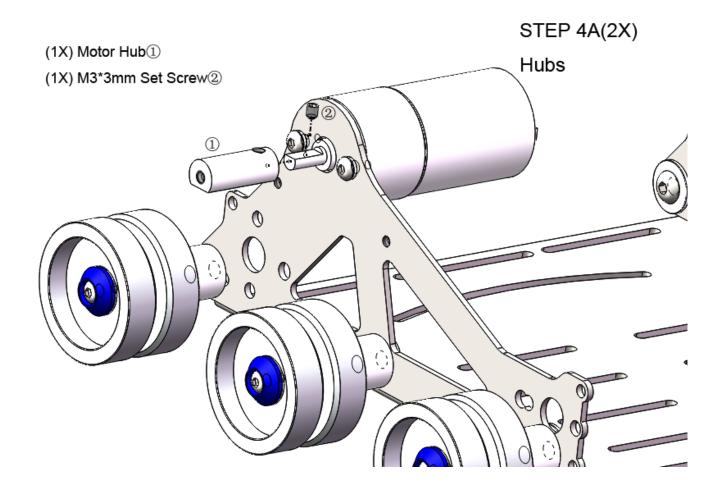
- (2X) M3\*6mm hex screws ①
- (2X) M3\*1mm gasket ②
- (1X) Gerar motor

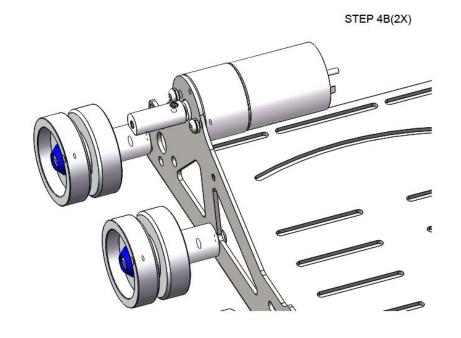




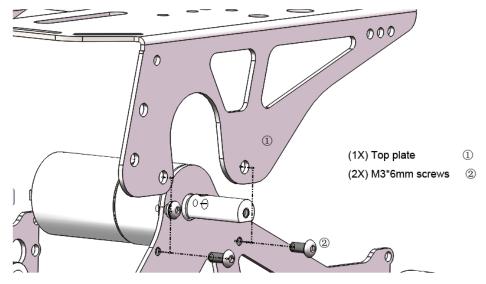
#### STEP 3B(2X)



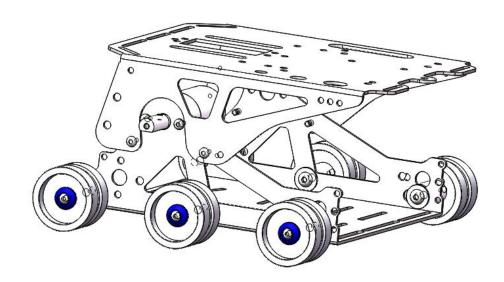


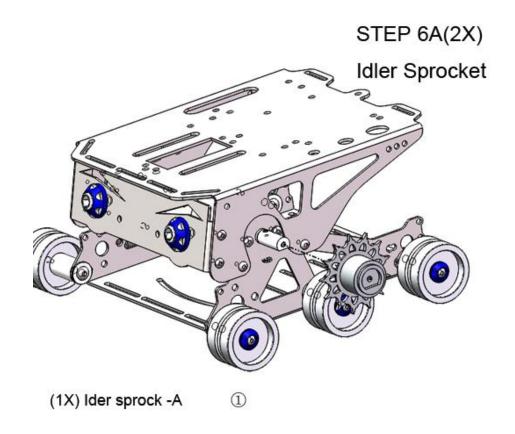


STEP 5A(2X) Top Plate

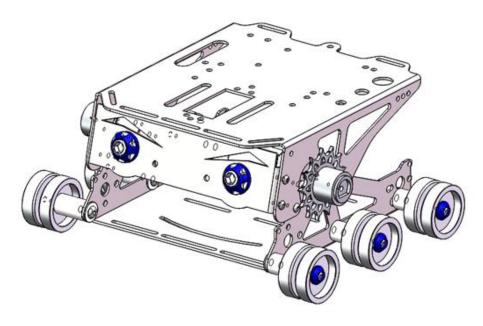


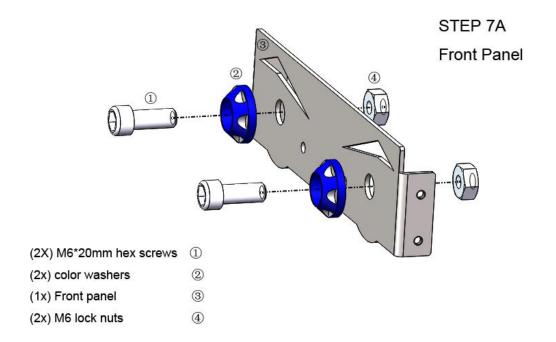
STEP 5B(2X)



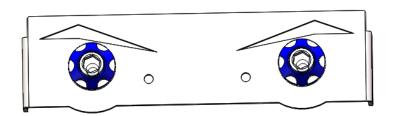




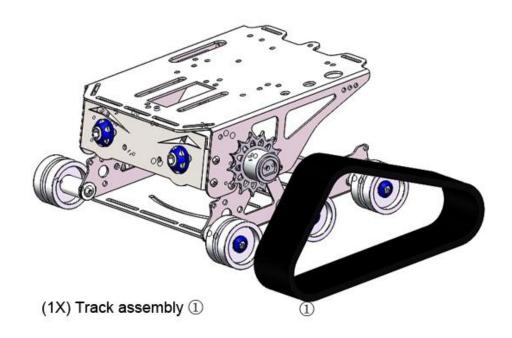


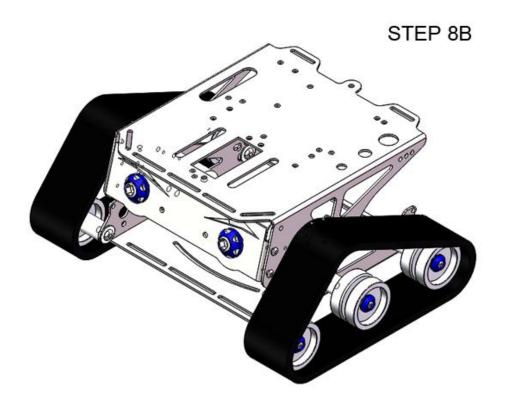


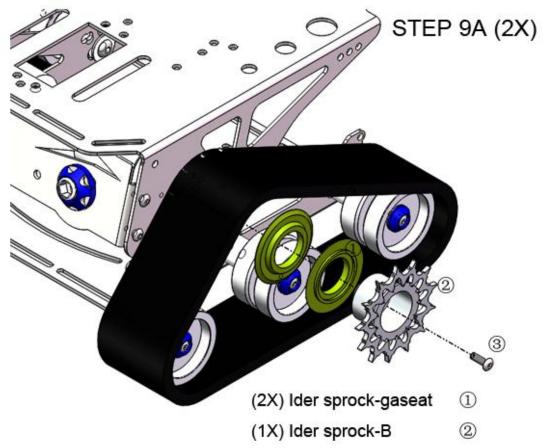
STEP 7B



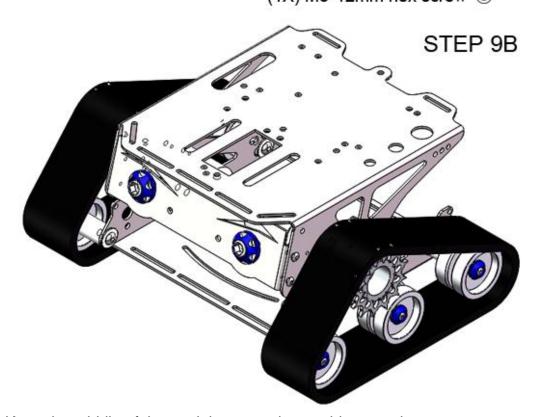
## STEP 8A (2X)







(1X) M3\*12mm hex screw ③



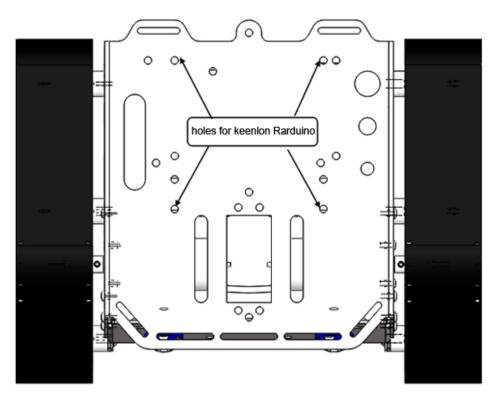
NOTE: Keep the middle of the track between the two ider sprock-gaseat.

NOTE: Adjust the position of the "secret screw" and keep the track a little tight.

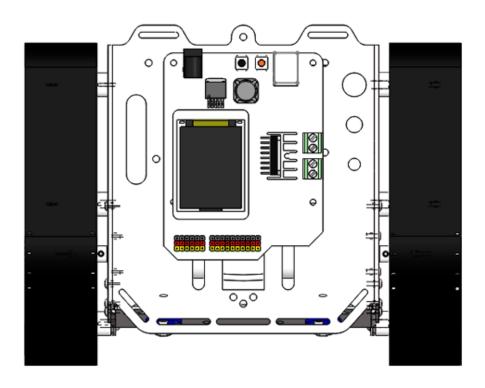
Complete!

# Electronic Devices Setup Guide

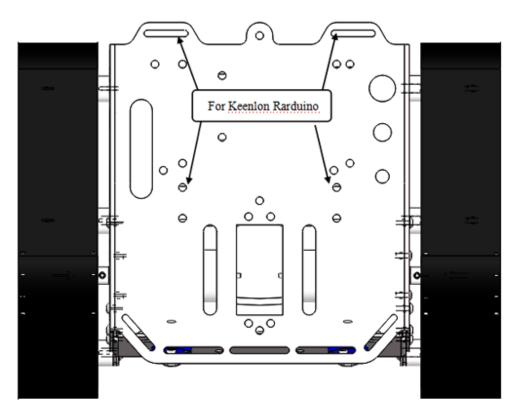
#### The first installation method



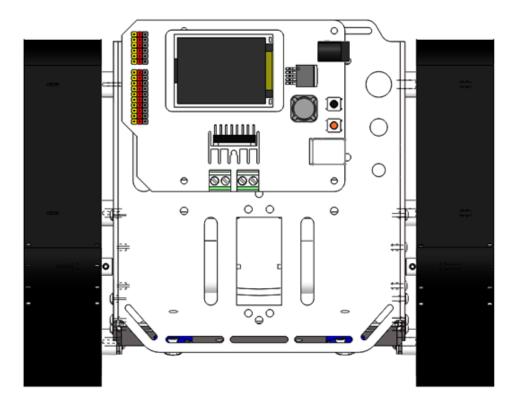
Top veiw

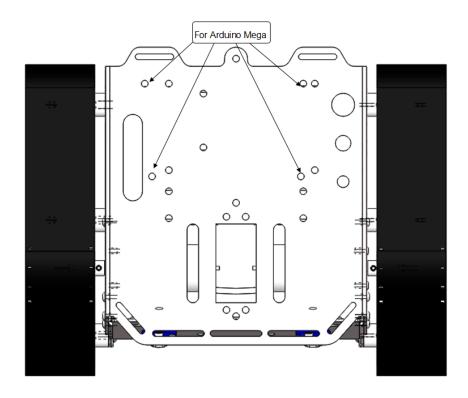


## The second installation method

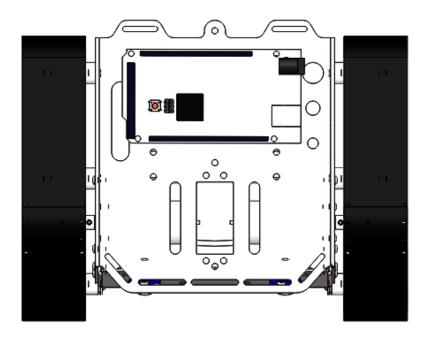


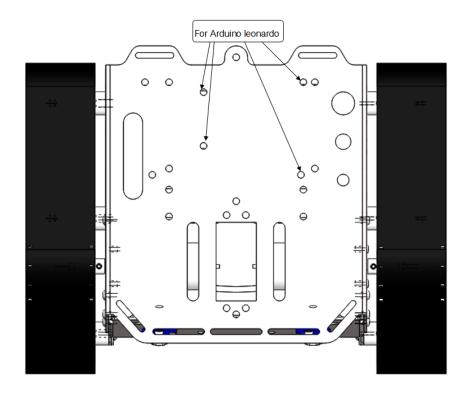
Top veiw



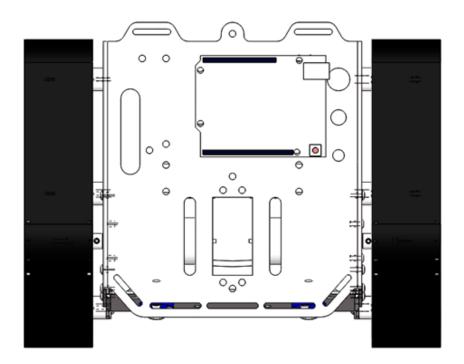


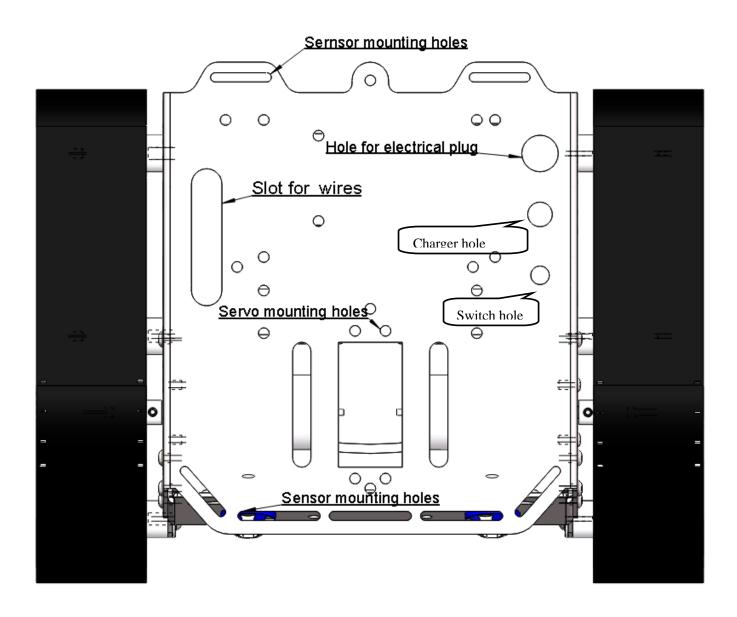
Mounting holes compatible with Arduino Mega





Mounting holes compatible with Arduino leonardo





# **DEMO**

